## Visual Object Recognition

Computational Models and Neurophysiological Mechanisms Neuro 130/230. Harvard College/GSAS 78454


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Computational Models and Neurophysiological Mechanisms Neurobiology 130/230. Harvard College/GSAS 78454

Note: no class on 09/04/2023 (Labor Day)
Class 1 [09/11/2023]. Introduction to Vision
Class 2 [09/18/2023]. The Phenomenology of Vision
Class 3 [09/25/2023]. Natural image statistics and the retina
Class 4 [10/02/2023]. Learning from Lesions
Note: no class on 10/09/2023 (Indigenous Day)
Class 5 [10/16/2023]. Primary Visual Cortex
Class 6 [10/23/2023]. Adventures into terra incognita
Class 7 [10/30/2023]. From the Highest Echelons of Visual Processing to Cognition
Class 8 [11/06/2023]. First Steps into in silico vision
Class 9 [11/13/2023]. Teaching Computers how to see
Class 10 [11/20/2023]. Computer Vision
Class 11 [11/27/2023]. Connecting Vision to the rest of Cognition [Dr. Will Xiao]
Class 12 [12/06/2023]. Visual Consciousness

FINAL EXAM, PAPER DUE 12/11/2023. No extensions.

# A mostly complete chart of 

## A big happy family of neural networks

https://towardsdatascience.com/the-mostly-complete-chart-of-neural-networks-explained-3fb6f2367464


Deep Convolutional Network (DCN)


Deconvolutional Network (DN)


Deep Residual Network (DRN)


## Deep convolutional neural networks: AlexNet



Krizhevsky et al 2012

## Formulation of the visual recognition problem


$\qquad$

## A more ambitious formulation



## A brief history of computational models

Hubel and Wiesel, simple and complex cells (1950s')

Neocognitron (Fukushima 1980)

HMAX (Poggio 1999), Work on MNIST (LeCun 1998)

Deep convolutional neural networks (circa 2012)

## Some of the typical computational operations

- Convolution
- Normalization
- ReLU
- Pooling


## The convolution operation

$$
f(t) * g(t)=\int_{-\infty}^{\infty} f(\tau) g(t-\tau) d \tau
$$



## Convolution and max pooling



## Convolution and max pooling



## ReLU

$$
f(u)=\max (0, u)
$$


input

## Max pooling

| 13 | 220 | 117 | 15 |
| :---: | :---: | :---: | :---: |
| 23 | 65 | 54 | 145 |
| 110 | 41 | 67 | 72 |
| 92 | 89 | 198 | 28 |

## The HMAX model



Riesenhuber and Poggio 1999

## The HMAX model



## The model captures the effects of clutter in visual responses



# The model captures selectivity and invariance in 

 V4 responses to curvatures

## The model approximates decoding of object information from IT cortex



## The model captures rapid recognition behavior



Serre et al 2007

## Traditional approaches to visual recognition



Example hand-crafted features

- Edges
- Textures
- Colors
- Corners
- Principal components
- Spatial frequency decomposition
- SIFT (Scale-invariant feature transform)


## Deep learning

 $\begin{array}{llllllllllllllllllllllllllll}0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0\end{array}$ $\begin{array}{llllllllllllllllllllllllllll}0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0\end{array}$ $0 \begin{array}{lllllllllllllllllllllllllll}0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0\end{array} 0$

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Image (or video)

## The credit assignment problem



## Back-propagation



## Back-propagation



## Back-propagation


(ifii)


## Is back-propagation biologically plausible?

Symmetric feed-forward and feed-back weights

Signed error signals

Large gradients

Feedback alters neuronal activity (and weights only indirectly)
Supervised learning requires many training examples

## Deeper and deeper



## Putting it all together




## To err is human and algorithmic



|  |  |  |  |  | tual | ateg |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
|  | 0.0 | ${ }^{0.0}$ | ${ }^{0.2}$ | 3 | 4 | 5 | ${ }^{0.0}$ | 7 |  | ${ }^{95.6}$ |
| 9 |  |  | 1 | 3 | 4 | 5 |  | 7 | 9 |  |
| 8 | ${ }^{0.5} 0$ | $\frac{0.4}{1 / 2}$ | ${ }_{11}^{2.7} \frac{1}{2}$ | ${ }^{1.0} 3$ | $\frac{0.4}{0.4}$ | ${ }^{1.5} 5$ | ${ }^{0.4} 6$ | $7$ | ${ }^{94.3}$ | 9 |
| 7 | $0$ | $\frac{0}{0.1}$ | ${ }^{0.6}$ | $\frac{0.6}{3}$ | 0.0 | ${ }^{0.2} 5$ | 0.0 | 89.3 | ${ }^{5} 8$ | ${ }^{0.3}$, |
| $\text { 충 } 6$ | ${ }^{0.8}$ | ${ }^{0.3} 1$ | ${ }^{1.1} 2$ | ${ }^{0.1} 3$ | ${ }^{0.8} 4$ | $5$ | ${ }^{97.0}$ | $\stackrel{0.2}{ } 7$ | ${ }^{0.8} 8$ | 4 |
| $\stackrel{0}{\pi}$ | $50$ | 0.0 | $2$ | $0_{5}^{0.7}$ | 0.0 | 91.7 | ${ }^{1.0} 6$ | 0.0 | 8 | 9 |
| $\text { O } 4$ | ${ }^{0.0} 0$ | 0.0 | ${ }^{0.5}$ | 0.0 | 94.7 | ${ }^{0.6}$ | ${ }^{0.3} 6$ | ${ }^{0.9} 7$ | ${ }^{0.6} 8$ | ${ }^{8} 9$ |
| $3$ | 0.0 | ${ }^{0.3}$ | $1.22$ | 95.9 | 0.0 | ${ }^{2.4} 5$ | ${ }^{0.0}$ | $1.0$ | 8 | 9 |
| 2 | 0.0 | ${ }^{0.1}$ | ${ }^{91.8}$ | $1.0$ | ${ }_{0.2} /$ | 5 | 0.0 | ${ }^{1.6} 7$ | 0.0 | 0.0 |
| 1 | 0.0 | 98.9 | ${ }^{0.8} 2$ | ${ }^{0.1} 3$ | 0.0 | ${ }^{0.1} 5$ | ${ }^{0.3} 6$ | ${ }^{1.6} 7$ | 8 | ${ }^{0.7}$ q |
| 0 | 98.4 | 0.0 | $1.12$ | 0.0 | $0_{4}^{0.2}$ | ${ }_{5}^{1.2}$ | $1 \frac{0.9}{6}$ | ${ }^{0.3} 7$ | ${ }^{0.4} 8$ | ${ }^{0.7} 9$ |

## Putting it all together




## CNNs in action: example



Layer visibility

Input layer
Convolution layer 1
Downsampling layer 1

Show
Show
Show

https://adamharley.com/nn_vis/cnn/3d.html

## Computational models versus biology

|  | Biology | Computer vision |
| :---: | :---: | :---: |
| Hierarchy | $\checkmark$ | $\checkmark$ |
| Receptive field increase through hierarchy | $\checkmark$ | $\checkmark$ |
| Convolution-like operations | $\checkmark$ | $\checkmark$ |
| Backpropagation | ? | $\checkmark$ |
| Supervised learning | ~ | $\checkmark$ |
| Unsupervised learning | $\checkmark$ | ~ |
| Interactions between areas | $\checkmark$ | $\sim$ |

## Summary

- Visual recognition ~ extraction of task-dependent adequate features plus read-out
- Computation emerges from combination of simple elementary functions: convolution, normalization, rectification, pooling
- Hierarchical models capture essential neural and behavioral properties of visual processing
- Weights can be learned via back-propagation
- Current models provide only a coarse approximation to the complexities of the visual system


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